- 5. [15 points] For each of the following, identify the statement as true or false by circling "True" or "False" as appropriate, and provide a short (one or two sentence) explanation indicating why that answer is correct.
  - **a.** [3 points] For the system  $x' = -xy + y^2$ ,  $y' = x^2 xy$ , the nonlinear trajectory in the phase plane with x(0) = -3 and y(0) = 0 lies on a circle centered on the origin.

True False

Solution: The system gives  $\frac{dy}{dx} = \frac{y'}{x'} = \frac{x(x-y)}{-y(x-y)} = -\frac{x}{y}$ . Separating and integrating, we get  $y \, dy = -x \, dx$ , so that  $x^2 + y^2 = 2c$ .

**b.** [3 points] For a linear differential operator  $L = \frac{d^2}{dt^2} + p(t)\frac{d}{dt} + q(t)$ , if  $y_1$  and  $y_2$  are different functions satisfying  $L[y_1] = L[y_2] = g(t) \neq 0$ , then, for any constants  $c_1$  and  $c_2$ ,  $y = c_1y_1 - c_2y_2$  satisfies L[y] = 0.

True False

Solution: Relying on the linearity of the operator,

$$L[y] = L[c_1y_1 - c_2y_2] = c_1L[y_1] - c_2L[y_2] = c_1g(t) - c_2g(t) = (c_1 - c_2)g(t),$$

which is zero only if  $c_1 - c_2 = 0$ .

c. [3 points] The solution to a differential equation my'' + ky = F(t) modeling the motion y of an undamped mechanical spring system with a periodic external force  $F(t) = F_0 \cos(\omega t)$  can always be written as  $y = A \cos(\omega_0 t - \delta_1) + B \cos(\omega t - \delta_2)$ , a sum of two oscillatory terms.  $(A, B, \omega_0, \delta_1 \text{ and } \delta_2 \text{ are constants.})$ 

True False

Solution: This is only true if the forcing frequence  $\omega$  is not equal to the natural frequency of the system,  $\omega_0 = \sqrt{k/m}$ . If  $\omega = \omega_0$ , we will have a growing solution  $y = A\cos(\omega_0 t - \delta_1) + Bt\cos(\omega_0 - \delta_2)$ .

d. [3 points] If  $\lambda^2 + p\lambda + q = 0$  is the characteristic equation of a constant-coefficient linear differential equation L[y] = g(t), then solving for  $Y(s) = \mathcal{L}\{y(t)\}$  will result in an expression involving a product of  $(s^2 + ps + q)^{-1}$  with other terms.

True False

Solution: The characteristic equation tells us that the differential equation is L[y] = y'' + py' + qy = g(t). The transform of this is  $s^2Y - sy(0) - y'(0) + psY - y(0) + qY = G(s)$ , and solving for Y will give the indicated result.

e. [3 points] If  $f(t) \neq 0$  has Laplace transform  $\mathcal{L}\{f(t)\} = F(s)$  and  $g(t) = \begin{cases} f(t), & 0 < t < c \\ 0, & t \geq c \end{cases}$ , then  $\mathcal{L}\{g(t)\} = (1 - e^{-sc})F(s)$ .

True False

Solution: The easiest way to see this is to look for  $h(t) = \mathcal{L}^{-1}\{(1 - e^{-sc})F(s)\} = f(t) - f(t-c)u_c(t)$ . Then, by definition,  $g(t) = (1 - u_c(t))f(t)$ , and in general  $h(t) \neq g(t)$ .