

6. [10 points] If we make a small typographical error when writing out the Lorenz system that we studied in lab 5, we obtain the system

$$\begin{aligned}x' &= \sigma(-x + y) \\y' &= ry - x - xz \\z' &= -bz + xy\end{aligned}$$

- a. [5 points] As with the Lorenz system, one critical point of this system is $(0, 0, 0)$. Find a linear system that approximates the system near $(0, 0, 0)$.

Solution: We know that this will be $\mathbf{x}' = \mathbf{J}(0, 0, 0) \mathbf{x}$, where \mathbf{J} is the Jacobian. This is

$$\begin{aligned}\mathbf{J}_0 &= \begin{pmatrix} \frac{\partial}{\partial x} \sigma(-x + y) & \frac{\partial}{\partial y} \sigma(-x + y) & \frac{\partial}{\partial z} \sigma(-x + y) \\ \frac{\partial}{\partial x} (ry - x - xz) & \frac{\partial}{\partial y} (ry - x - xz) & \frac{\partial}{\partial z} (ry - x - xz) \\ \frac{\partial}{\partial x} (-bz + xy) & \frac{\partial}{\partial y} (-bz + xy) & \frac{\partial}{\partial z} (-bz + xy) \end{pmatrix} \Big|_{(0,0,0)} \\ &= \begin{pmatrix} -\sigma & \sigma & 0 \\ -1 - z & r & -x \\ y & x & -b \end{pmatrix} \Big|_{(0,0,0)} = \begin{pmatrix} -\sigma & \sigma & 0 \\ -1 & r & 0 \\ 0 & 0 & -b \end{pmatrix}.\end{aligned}$$

And our system is, with $\mathbf{x} = (x \ y \ z)^T$, $\mathbf{x}' = \mathbf{J}_0 \mathbf{x}$.

Alternately, because we are linearizing at $(0, 0, 0)$ and all terms are polynomial, we can just drop the nonlinear terms from the system, obtaining the same result.

- b. [5 points] If $b = 5$, $\sigma = 1$, and $r = 1/4$, the eigenvalues and eigenvectors of the coefficient matrix of the linearized system you found in (a) are approximately $\lambda_1 = -5$ and $\lambda_{2,3} = -\frac{3}{8} \pm \frac{7}{9}i$, with $\mathbf{v}_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, and $\mathbf{v}_{2,3} = \begin{pmatrix} \frac{5}{8} \pm \frac{6}{7}i \\ 1 \\ 0 \end{pmatrix}$. Describe phase space trajectories in this case. If we start with an initial condition $(x, y, z) = (0.5, 0.5, 0)$, sketch the trajectory in the phase space.

Solution: We note that the first eigenvalue is a much larger (in magnitude) negative real value than the real part of the other two; thus, we expect that to decay much faster than the other. Because this is associated with the eigenvector $\mathbf{v}_1 = (0 \ 0 \ 1)^T$, this means that the trajectories will rapidly decay into the xy -plane. Once there, they will be spiral trajectories. We note that the linearized system gives $\begin{pmatrix} x \\ y \end{pmatrix}' = \begin{pmatrix} -1 & 1 \\ -1 & 1/4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$, so starting from $(x, y) = (1, 1)$, $(x', y') = (0, -3/4)$ and the trajectory must be moving clockwise. Thus we have a clockwise spiral in the xy -plane, shown below.

